

8.2 Wiener deconvolution

- Model of Observation :

$$y(t) = h(t) * \hat{x}(t) + n(t) \quad (1)$$

$$(y(t), h(t) : \text{known})$$

$$Y(f) = H(f) \cdot \hat{X}(f) + N(f) \quad (2)$$

$$\left(\hat{X} = \frac{Y-N}{H} \right)$$

$$|N(f)| \sim |N'(f)| \quad (|N'(f)| : \text{known}) \quad (3)$$

- Estimation $\tilde{x}$:

$$\tilde{X}(f) = \Psi_x(f) Y(f) \quad (\Psi_x \in \mathbb{C}) \quad (4)$$

$$\text{minimize } E = \int \underbrace{\left| \tilde{X} - \hat{X} \right|^2}_{=I} df \quad (5)$$

$$\rightarrow \frac{\partial E}{\partial \Psi_x} = 0 \quad (6)$$

$$\begin{aligned} I &= \left| \tilde{X} - \hat{X} \right|^2 = \left| \Psi_x Y - \frac{Y-N}{H} \right|^2 \\ &= \left| \left(\Psi_x - \frac{1}{H} \right) Y + \frac{N}{H} \right|^2 \\ &= \left| \left(\Psi_x - \frac{1}{H} \right) Y \right|^2 + \frac{|N|^2}{|H|^2} \\ &\quad + \left(\Psi_x - \frac{1}{H} \right) Y \frac{N^*}{H^*} + \left(\Psi_x^* - \frac{1}{H^*} \right) Y^* \frac{N}{H} \\ &\quad \left(\underbrace{\left(\Psi_x - \frac{1}{H} \right) Y \frac{N^*}{H^*}}_{\text{Integral}=0} \quad (\text{Eq.(2)}) \right. \\ &\quad \quad = \left(\Psi_x - \frac{1}{H} \right) (H \hat{X} + N) \frac{N^*}{H^*} \\ &\quad \quad = \left(\Psi_x - \frac{1}{H} \right) \frac{H}{H^*} \hat{X} N^* + \left(\Psi_x - \frac{1}{H} \right) \frac{1}{H^*} |N|^2 \left. \right) \end{aligned}$$

$$E = \int I(f) df = \int I'(f) df$$

$$\begin{aligned} I' &= \left| \left(\Psi_x - \frac{1}{H} \right) Y \right|^2 - \frac{|N|^2}{|H|^2} \\ &\quad + \Psi_x \frac{|N|^2}{H^*} + \Psi_x^* \frac{|N|^2}{H} \end{aligned}$$

Wiener deconvolution

$$\frac{\partial E}{\partial \Psi_x} = 0 \text{ or } \frac{\partial E}{\partial \Psi_x^*} = 0$$

$$E = \int I'(f) df$$

$$I' = \left| \left(\Psi_x - \frac{1}{H} \right) Y \right|^2 - \frac{|N|^2}{|H|^2} + \Psi_x \frac{|N|^2}{H^*} + \Psi_x^* \frac{|N|^2}{H}$$

$$\left(\begin{array}{l} \frac{\partial}{\partial \Psi_x} \left(\left| \left(\Psi_x - \frac{1}{H} \right) Y \right|^2 \right) \\ = \frac{\partial}{\partial \Psi_x} \left(\left(\Psi_x^* - \frac{1}{H^*} \right) \left(\Psi_x - \frac{1}{H} \right) |Y|^2 \right) \\ = \left(\Psi_x^* - \frac{1}{H^*} \right) |Y|^2 \end{array} \right)$$

$$\frac{\partial I'}{\partial \Psi_x^*} = \left(\Psi_x - \frac{1}{H} \right) |Y|^2 + \frac{|N|^2}{H} = 0$$

$$\rightarrow \Psi_x = \frac{1}{H} \underbrace{\frac{|Y|^2 - |N|^2}{|Y|^2}}_{= \Phi_y \text{ if } |N|=|N'|}$$

Wiener deconvolution :

$$\Psi_x(f) = \frac{\Phi_y(f)}{H(f)} \quad (7)$$

$$\Phi_y(f) = \frac{|Y|^2 - |N'(f)|^2}{|Y(f)|^2} \quad (8)$$

$$\begin{aligned} \tilde{X}(f) &= \Psi_x(f) Y(f) \\ &= \frac{1}{H(f)} \Phi_y(f) Y(f) \end{aligned} \quad (9)$$

Spectrum of Wiener deconvolution is equivalent to the divided spectrum of the spectrum applied Wiener filter to $Y(f)$.

In the ideal case of $N'(f) = N(f)$

$$\begin{aligned}
 (N' = N) \\
 \Psi_x &= \frac{1}{H} \Phi_y \\
 &= \frac{1}{H} \frac{|Y|^2 - |N|^2}{|Y|^2} = \frac{1}{H} \frac{|\hat{Y}|^2}{|\hat{Y}|^2 + |N|^2} \\
 &= \frac{H^* |\hat{X}|^2}{|H|^2 |\hat{X}|^2 + |N|^2} \quad (10)
 \end{aligned}$$

- $H \neq 0$ and $N = 0$:

$$\Psi_x = \frac{1}{H} \rightarrow \tilde{X} = \frac{Y}{H} = \hat{X}$$

(Ideal case)

- $H = 0$ and $N \neq 0$:

$$\Psi_x = 0 \rightarrow \tilde{X} = 0$$

(Cannot restore)

- $H = 0$ and $N = 0$:

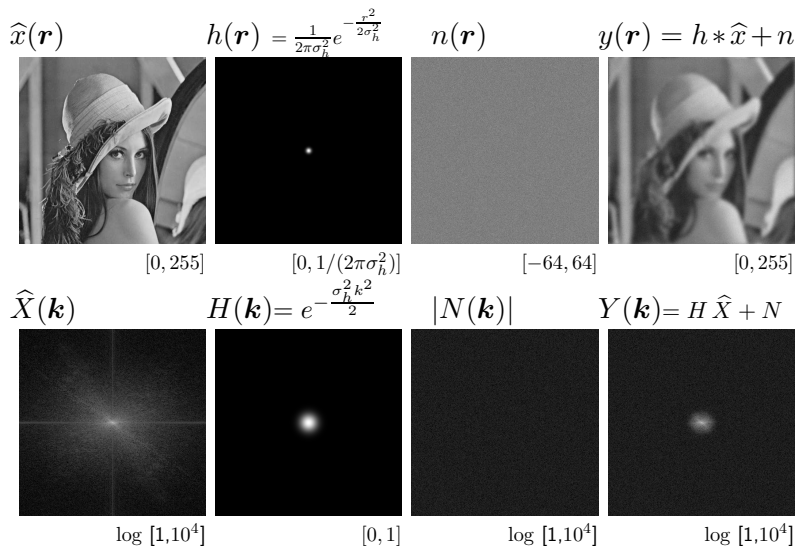
$$\begin{aligned}
 &\lim_{H \rightarrow 0} \left\{ \lim_{N \rightarrow 0} \left| \frac{H^* |\hat{X}|^2}{|H|^2 |\hat{X}|^2 + |N|^2} \right| \right\} \\
 &= \lim_{H \rightarrow 0} \left\{ \left| \frac{1}{H} \right| \right\} = \infty \\
 &\lim_{N \rightarrow 0} \left\{ \lim_{H \rightarrow 0} \left| \frac{H^* |\hat{X}|^2}{|H|^2 |\hat{X}|^2 + |N|^2} \right| \right\} = 0
 \end{aligned}$$

Estimation is impossible.

(It takes different values, if the path to take limitation is different.)

If $H = 0$, $\tilde{X}$ cannot be determined.
 $\rightarrow$ (Consider as $\tilde{X}(f) = 0$)
 to obtain $\tilde{x}(t)$.

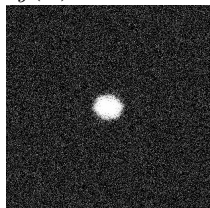
Example of Wiener deconvolution (Input : $\sigma_h = 5$, $\sigma_n = 5$)



Example of Wiener deconvolution (Result (failed case))

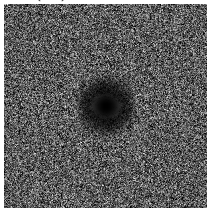
$$(|N'(f)| = \sigma'_n = 5)$$

$$\Phi_y(\mathbf{k})$$



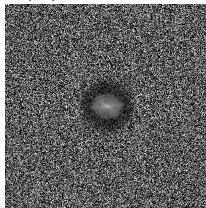
$[0, 1]$

$$\Psi_x(\mathbf{k})$$



$\log [1, 10^{105}]$

$$\tilde{X}(\mathbf{k})$$



$\log [1, 10^{105}]$

$$\tilde{x}(\mathbf{r})$$



$[0, 10^{105}]$

Since $|\Psi_x(\mathbf{k})|$ includes very large spectrum, $\tilde{X}(\mathbf{k})$ diverges, and $\tilde{x}(\mathbf{r})$ diverges.

Reason of large filter gain.

- $H = 0$ and $N' \neq N$

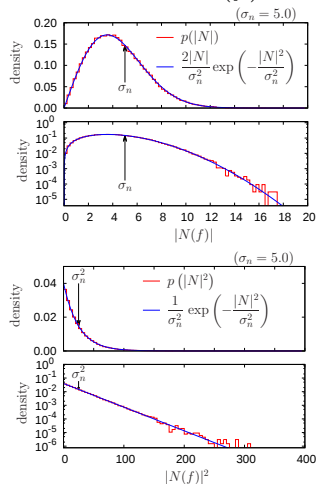
$$\begin{aligned}\Psi_x &= \lim_{H \rightarrow 0} \frac{1}{H} \Phi_y \\ &= \lim_{H \rightarrow 0} \frac{1}{H} \frac{\text{Pos}\{|Y|^2 - |N'|^2\}}{|Y|^2} \\ &= \lim_{H \rightarrow 0} \frac{1}{H} \frac{\text{Pos}\{|H\hat{X} + N|^2 - |N'|^2\}}{|H\hat{X} + N|^2} \\ &= \lim_{H \rightarrow 0} \frac{1}{H} \frac{\text{Pos}\{|N|^2 - |N'|^2\}}{|N|^2}\end{aligned}$$

$$\text{Pos}\{F\} \equiv \max\{F, 0\}$$

$$|\Psi_x| = \begin{cases} \infty & (|N| > |N'|) \\ 0 & (|N| \leq |N'|) \end{cases}$$

→ Not continuous

Prob. dens. of $N(f)$



Methods to suppress divergence of filter gain.

- Specify large $|N'|$

$$\Psi'_x = \frac{1}{H} \frac{\text{Pos} \{ |Y|^2 - \alpha |N'|^2 \}}{|Y|^2} \quad (\alpha > 1)$$

- Limitation of domain

$$\Psi'_x(\mathbf{k}) = \Theta \{ |k| \leq k_{\max} \} \Psi_x(\mathbf{k})$$

$$\left(\Theta \{ C \} \equiv \begin{cases} 1 & (C \text{ is true}) \\ 0 & (C \text{ is false}) \end{cases} \right)$$

- Limitation of range

$$\Psi'_x = \Theta \{ |\Psi(k)| \leq \Psi_{\max} \} \Psi_x(k)$$

- Limitation of $|H|$

$$\Psi'_x = \Theta \{ |H| > H_{\min} \} \Psi_x$$

- Inspection of neighbors

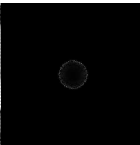
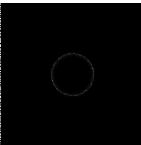
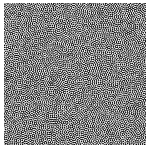
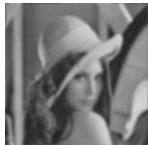
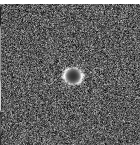
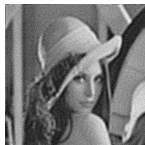
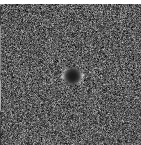
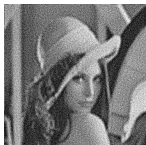
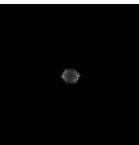
$$\Psi'_x(\mathbf{k}) = \Theta \left\{ \frac{M_0(\mathbf{k})}{M_a(\mathbf{k})} > r_{0\min} \right\} \Psi_x(\mathbf{k})$$

- $M_a(\mathbf{k})$ is the number of pixels neighboring $\mathbf{k}$.
- $M_0(\mathbf{k})$ is the number of pixels with $\Phi_y(\mathbf{k}') = 0$ within the pixels neighboring $\mathbf{k}$.

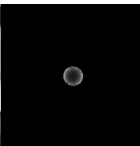
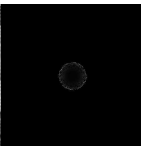
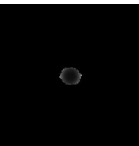
Suppression of divergence in Wiener Deconvolution (e.g.)

Before Deconv.

True

 $k_{\max} = 0.15$: Divergent $k_{\max} = 0.10$: Periodic Pattern $\alpha = 4$: Blurring $\Psi_{\max} = 10$: Noisy $\Psi_{\max} = 5$: Noisy

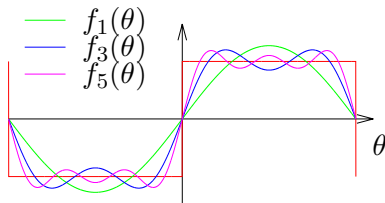
Insp. Neigh. : Ringing

 $H_{\min} = 0.01$: Peri. Patt. $H_{\min} = 0.1$: Peri. Patt., Ring.

Reason of errors in Wiener deconvolution

- Divergent
Insufficient reduction of filter gain for small H .
- Blurring
Over filtering of high freq. component.
- Periodic Pattern
Insufficient filtering for a certain component.
- Noisy
Insufficient filtering of high freq. component.

- Ringing
Ghost appears along edges.
Caused by Fourier transform with finite terms' truncation.
 $\Leftrightarrow$ Gibbs phenomenon
(Impossible to avoid ringing.)



8.3 Estimation of Response function $H(f)$

$$Y(f) = H(f) \cdot \hat{X}(f) + N(f)$$

$$\tilde{X}(f) = \frac{1}{H(f)} \Phi_y(f) Y(f)$$

$H(f)$: Function is known, but parameter of the function is unknown.

$$\left(\begin{array}{l} \text{e.g.: } H(f) = e^{-\frac{f^2}{2\sigma_f^2}} \\ (\sigma_f \text{ is unknown}) \end{array} \right)$$

- Determine the parameter by least square fitting, and compute $\tilde{H}(f)$
- The data for the least square fitting is flatten data by noise probability density function in the domain where the noise is dominant.

$$\tilde{X}'(f) = \frac{1}{\tilde{H}(f)} \Phi_y(f) Y(f)$$

Least square fitting to Gaussian function

- Fitting function (Estimated Value)

$$\tilde{f}(x_i; a, b) = ae^{-bx_i^2}$$

- Observed value

$$(x_i, f_i) \quad i \in \{1, \dots, N\}$$

- Residual $\Delta f_i = f_i - \tilde{f}(x_i)$

- Average of Square Residual

$$E = \overline{(\Delta f)^2}$$

- minimize E

- In general method, the normal equations become non-linear equations.

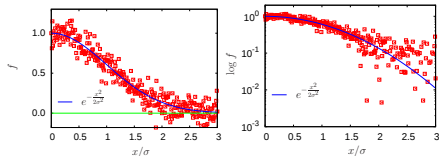
→Complex

- Mapping from f to $F = \log f$.

$$\tilde{F}_i(x_i; a, b) = \log a - bx_i^2$$

- quadratic equation
- Expected error for f and that for F are different.
→ It should be consider the weight.

$$E = \overline{f^2(\Delta \log f)^2}$$



Weighted least square method

Weight $\equiv$ reliability of data

$$E = \overline{w_i (f_i - \tilde{f}_i)^2}$$

Low reliability of the data with the large scattering.

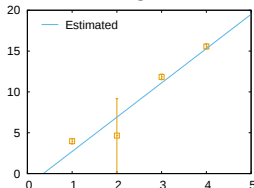
$$E \left[(f_i - \tilde{f}_i)^2 \right] \sim E \left[(f_i - \hat{f}_i)^2 \right] = \sigma_{f_i}^2$$

$$\rightarrow \frac{1}{\sigma_{f_i}^2} E \left[(f_i - \tilde{f}_i)^2 \right] \sim 1(\text{constant})$$

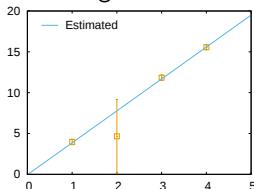
$$\rightarrow \text{Independent of } i \quad \rightarrow \quad \therefore w_i = \frac{1}{\sigma_{f_i}^2}$$

$$E = \frac{1}{\sigma_{f_i}^2} (f_i - \tilde{f}_i)^2 \quad (1)$$

Without weight



With weight



Mapping of variable in least square method

$$E = \frac{1}{\sigma_{f_i}^2} (f_i - \tilde{f}_i)^2 \quad (2)$$

In the case of $F_i = F(f_i)$,

$$\begin{aligned} f_i - \tilde{f}_i &= \Delta f_i = \Delta F_i \frac{\Delta f_i}{\Delta F_i} \\ &\simeq (F_i - \tilde{F}_i) \left. \frac{df}{dF} \right|_i \\ E &= \frac{1}{\left(\frac{dF}{df} \right)_i^2 \sigma_{f_i}^2} (F_i - \tilde{F}_i)^2 \quad (3) \end{aligned}$$

$\left| \frac{dF}{df} \right|$ shows a magnification factor of error bar.

If $F = \log f$,

$$\begin{aligned} \frac{dF}{df} &= \frac{1}{f} \\ E &= \frac{f_i^2}{\sigma_{f_i}^2} (\log f_i - \log \tilde{f}_i)^2 \end{aligned}$$

- $f = \hat{f} + n$
 n : white $\rightarrow \sigma_n^2 = \text{const.}$
- $E = \frac{1}{\sigma_n^2} f_i^2 (\log f_i - \log \tilde{f}_i)^2$
- Larger f has larger weight.